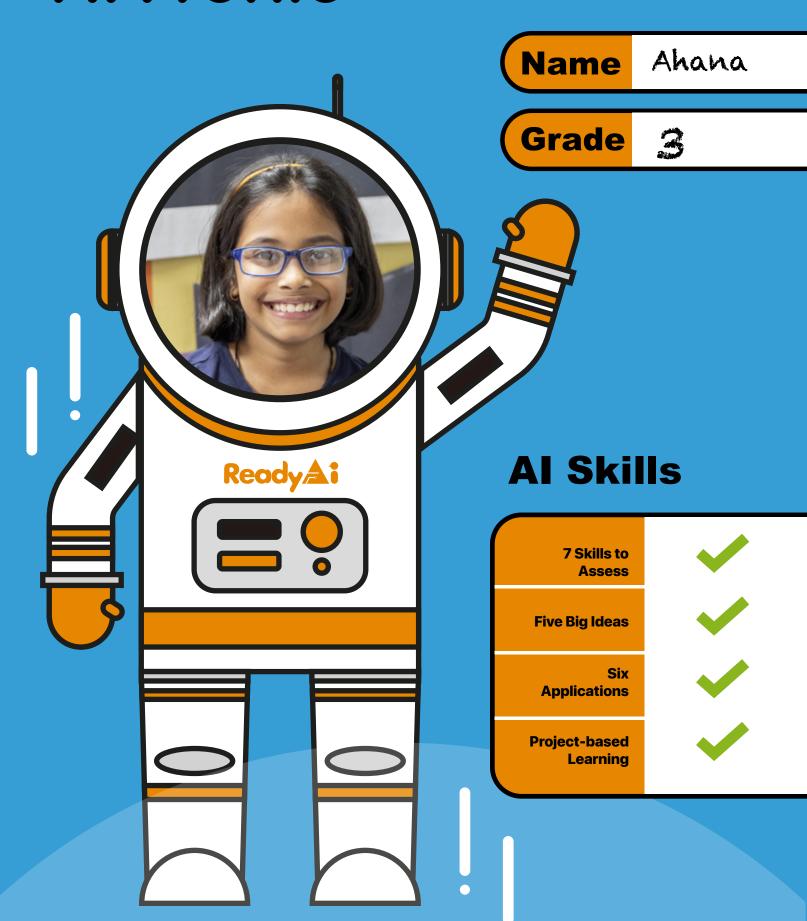


AHANA'S AI LEARNING REPORT



Al Profile



What You Learned Learned

7 Skills to assess











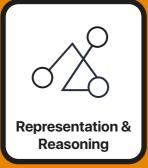




















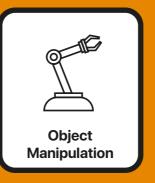


























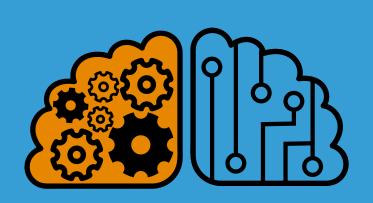








What Al is What Al is not



2

Robots completing tasks vs. Al making decisions

3

Introduction to Five Big Ideas in AI (Perception, Decision-Making, Learning, Human-AI Interaction and Societal Impact)



1

Computer vision works by detecting edges, lines, and patterns



?

2

Cozmo can differentiate his three cubes by recognizing their unique markers

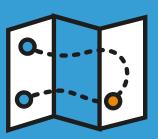
3

Facial detection involves extracting facial landmarks such as eyes and nose



1

Cozmo (and other Al units) navigate through the world using path-planning algorithms

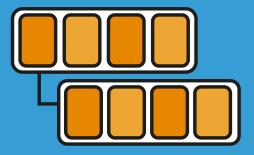


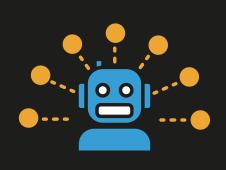
2

What objects Cozmo can and cannot manipulate and why

3

In Calypso and other programming languages like Python, we use **indentation** to distinguish structure



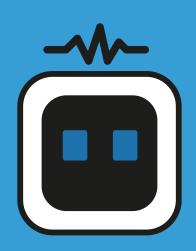


4

Calypso uses parallel programming which means that under each **state**, multiple processing elements will run simultaneously to solve a problem

1

Cozmo (and other Al units)
have conversations with us
using speech recognition and
speech generation technology



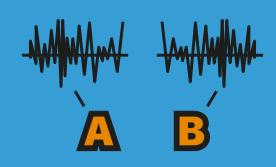


2

Computers understand language by extracting features from recordings and decoding them with acoustic and language models

3

An Al unit pronounces an English word by producing the phonemes that make up that word, one by one



Timeline

Oct 9, 2019

Lesson 2

You coded a short demo that simulates how Al can promote manufacturing safety. You also learned about how facial recognition works at the basic level.

Oct 2, 2019

Lesson 1

You played with Cozmo, our Al robot and coded your first line of code in Calypso!

Lesson 4

Oct 23, 2019

You learned about speech recognition and speech generation. To finish out the beginner course, you created a stimulation in which Cozmo acted as a firefighter, employing at least three Al applications.

Oct 16, 2019

Lesson 3

You programmed Cozmo to move around an obstacle cube and then move toward a goal cube.

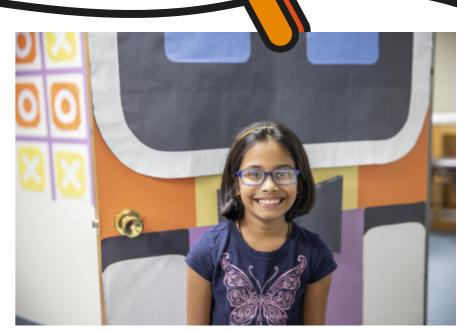
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Reody Ai

